Shenzhen Omni Sharing scooter IOT User Manual

Manualsum, simplified manuals

Table of Contents

- Shenzhen Omni Sharing scooter IOT User Manual
 - Production description
 - APP installtion and log in
 - Lock/unlock manual:
 - <u>IOT controller should work with smart phone</u>. Requirements for <u>smart phone</u>:
 - Introduction of app interfaces

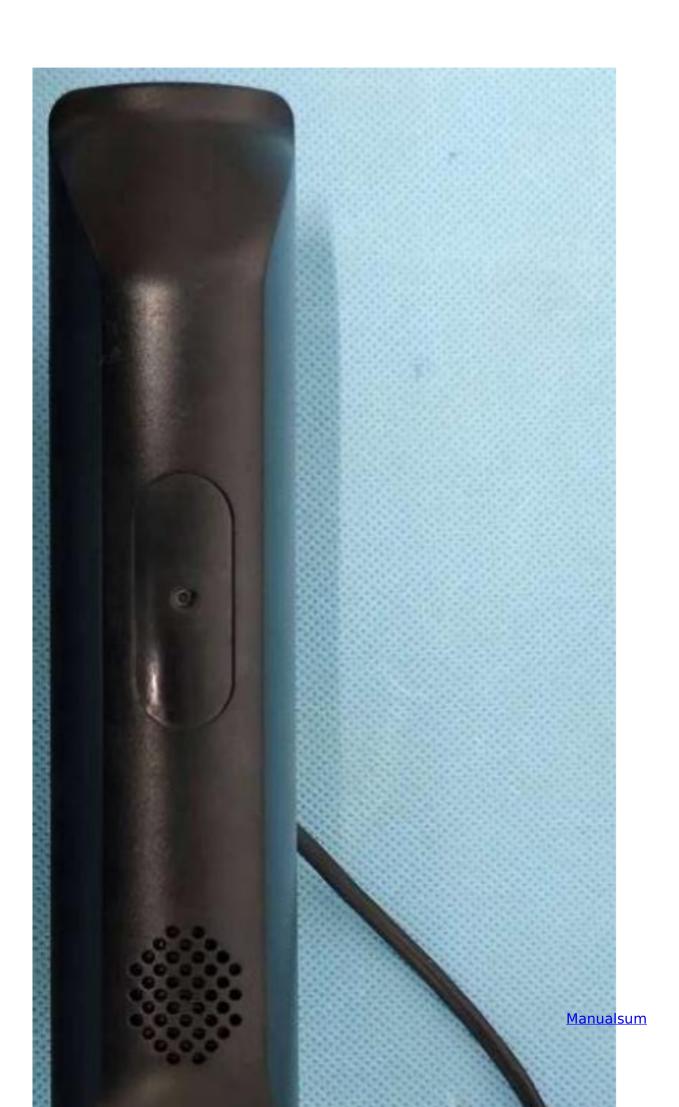
Shenzhen Omni Sharing scooter IOT User Manual

Shenzhen Omni Sharing scooter IOT User Manual

Omni Intelligent Technology Sharing scooter IOT User Manual

FCC id: 2AI2O-M154IOT

Operation manual for sharing scooter IOT





Production description

This is a IOT controller for sharing scooter which via 4G, GPS, BLE to set up communication between app to control scooter lock/unlock.Cloud server account riding time and charge automatically.

APP installtion and log in

- 1. Download app.
- 2. Registration and Log in ,which need to be done with network, account should be valid phone number ,
- 3. Deposit, Toll charge.

Lock/unlock manual:

- 1. Open Bluetooth.
- 2. StartAPP, click the middle QR code button below the APP., enter into QR code scan page, scan the QR code of IOT controller, IOT will be unlocked automatically when apps get QR code informations, then enter into riding status.
- 3. Click lock when riding is finished, cloud server will stop IOT and charge when receive lock request from IOT.

IOT controller should work with smart phone. Requirements for smart phone:

Over Android 4.3, hardware support 4. 0BLE, Optimal screen resolution 1280×720; over IOS 7.1, over iphone 4s

Introduction of app interfaces



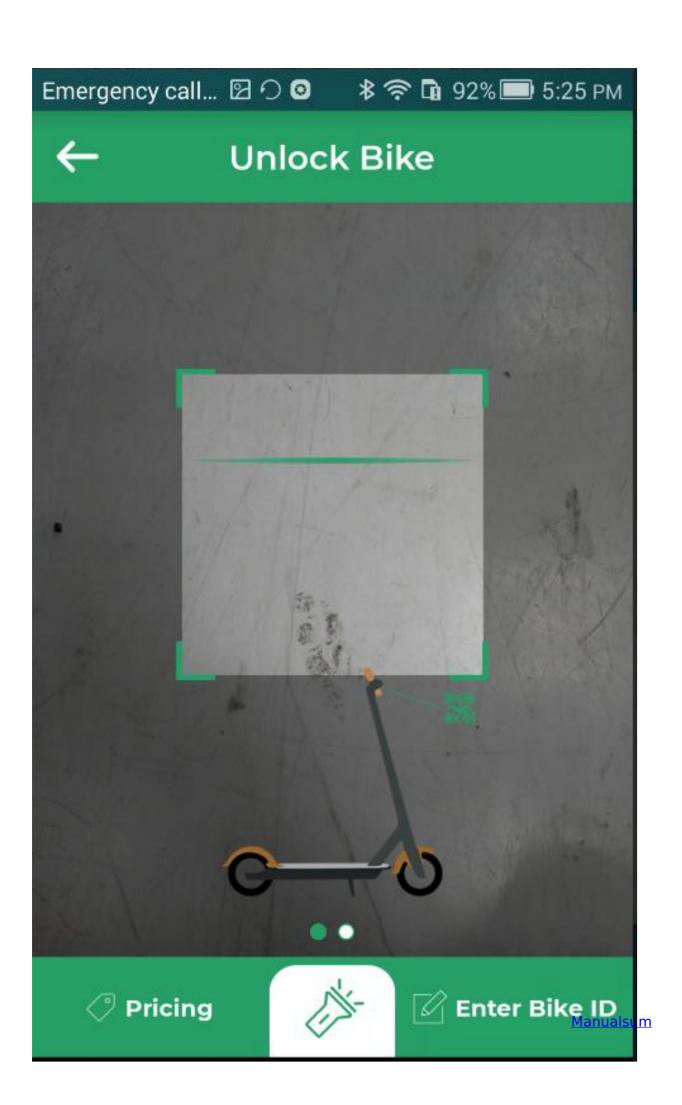
OmniRide won't run without Google Play services, which are not supported by your device.







main page



Scan QR code page

Emergency call... o



Start your Ride

Don't close the app or turn off Bluetooth until you lock the bike and receive the trip summary.

00:24

Power

100%

Speed

0.0km/h

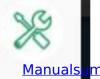
Mode

Medium Speed

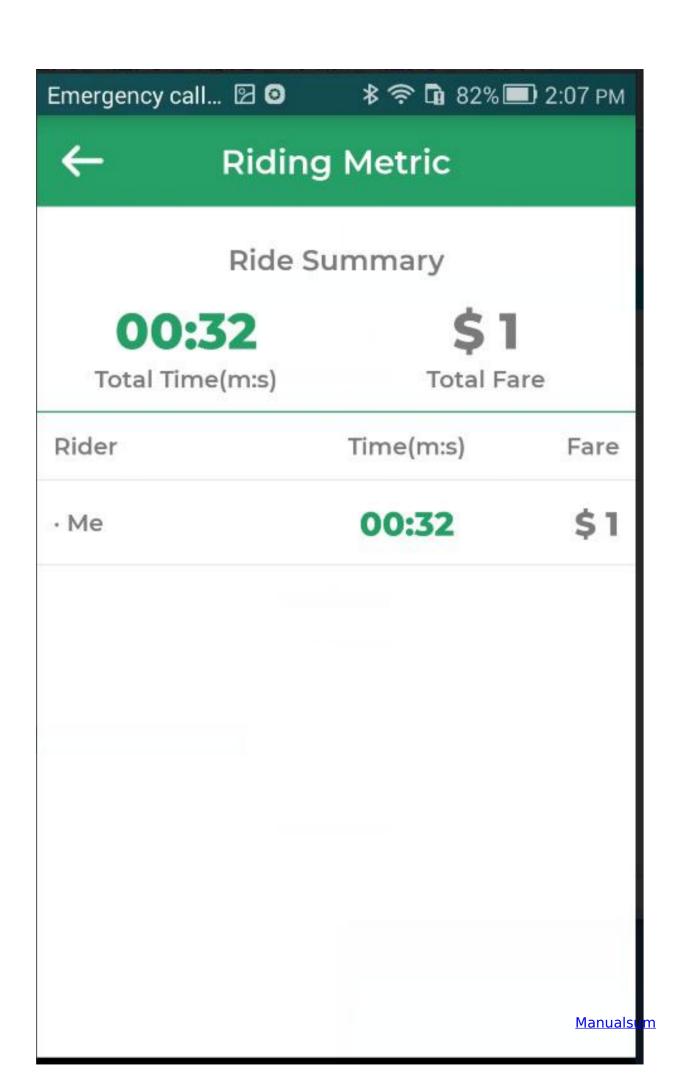
Lock & Bill







Unlocking car page



End successful deduction page